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A method for guidance and control of an autonomous vehicle in problems of border patrolling and obstacle avoidance	Matveev, Alexey S.; Teimoori, Hamid; Savkin, Andrey V.	AUTOMATICA	47	3	515-524	2011	40	5.451
Navigation of a unicycle-like mobile robot for environmental extremum seeking	Matveev, Alexey S.; Teimoori, Hamid; Savkin, Andrey V.	AUTOMATICA	47	1	85-91	2011	33	5.451
Range-only measurements based target following for wheeled mobile robots	Matveev, Alexey S.; Teimoori, Hamid; Savkin, Andrey V.	AUTOMATICA	47	1	177-184	2011	30	5.451
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Non-constant discounting and differential games with random time horizon	Marin-Solano, Jesus; Shevkoplyas, Ekaterina V.	AUTOMATICA	47	12	2626-2638	2011	11	5.451
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Synthesis of Razumikhin and Lyapunov-Krasovskii approaches to stability analysis of time-delay systems	Medvedeva, Irina V.; Zhabko, Alexey P.	AUTOMATICA	51		372-377	2015	8	5.451
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